Algorithmic Derivatives

for $GAUSS^{TM}$ Version 1.0

Aptech Systems, Inc.

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Chapter 1

Installation

1.1 **UNIX**

If you are unfamiliar with UNIX, see your system administrator or system documentation for information on the system commands referred to below.

1.1.1 Download

- 1. Copy the .tar.gz file to /tmp.
- 2. Unzip the file.

```
\verb"gunzip" appxxx.\texttt{tar.gz}"
```

3. cd to your **GAUSS** or **GAUSS Engine** installation directory. We are assuming /usr/local/gauss in this case.

```
cd /usr/local/gauss
```

4. Untar the file.

```
tar xvf /tmp/appxxx.tar
```

1.1.2 CD

1. Insert the Apps CD into your machine's CD-ROM drive.

- 2. Open a terminal window.
- 3. cd to your current **GAUSS** or **GAUSS Engine** installation directory. We are assuming /usr/local/gauss in this case.

cd /usr/local/gauss

4. Use tar to extract the .tar files found on the CD. For example:

```
tar xvf /cdrom/apps/app_myapps_1.0_unix.tar
```

However, note that the paths may be different on your machine.

Documentation for the application(s) can be found in the apps/MANUALS subdirectory of the CD.

1.1.3 Floppy

1. Make a temporary directory.

mkdir /tmp/workdir

2. cd to the temporary directory.

cd /tmp/workdir

3. Use tar to extract the files.

```
tar xvf device\_name
```

If this software came on diskettes, repeat the tar command for each diskette.

4. Read the README file.

more README

5. Run the install.sh script in the work directory.

```
./install.sh
```

The directory the files are installed to should be the same as the install directory of **GAUSS** or the **GAUSS Engine**.

6. Remove the temporary directory (optional).

$1.2 \quad \text{Windows/NT/2000}$

1.2.1 Download

Unzip the .zip file into your GAUSS or GAUSS Engine installation directory.

1. INSTALLATION

1.2.2 CD

- 1. Insert the Apps CD into your machine's CD-ROM drive.
- 2. Unzip the .zip files found on the CD to your **GAUSS** or **GAUSS Engine** installation directory, using your current .zip file extraction utility.

Documentation for the application(s) can be found in the MANUALS subdirectory of the CD.

1.2.3 Floppy

- 1. Place the diskette in a floppy drive.
- 2. Call up a DOS window
- 3. In the DOS window log onto the root directory of the diskette drive. For example:

A:<enter>
cd\<enter>

4. Type: ginstall source_drive target_path

source_drive Drive containing files to install

with colon included

For example: **A:**

target_path Main drive and subdirectory to install

to without a final \

For example: C:\GAUSS

A directory structure will be created if it does not already exist and the files will be copied over.

 $target_path \$ source code files $target_path \$ library files $target_path \$ examples example files

1.3 Differences Between the UNIX and Windows/NT/2000 Versions

• If the functions can be controlled during execution by entering keystrokes from the keyboard, it may be necessary to press *Enter* after the keystroke in the UNIX version.

• On the Intel math coprocessors used by the Windows/NT/2000 machines, intermediate calculations have 80-bit precision, while on the current UNIX machines, all calculations are in 64-bit precision. For this reason, **GAUSS** programs executed under UNIX may produce slightly different results, due to differences in roundoff, from those executed under Windows/NT/2000.

Chapter 2

Getting Started

2.1 Setup

ALGORITHMIC DERIVATIVES or **AD** is a program which takes a **GAUSS** procedure that computes a function and produces a **GAUSS** procedure for computing its derivative.

AD needs the Java Runtime Environment (JRE) V1.4.1 or a later version in order to run. If you do not already have JRE 1.4.1 installed, you can download it for free from Sun at http://java.sun.com/j2se/1.4.1/download.html Follow the instructions to install the JRE and add the bin directory containing the java.exe to your path. E.g. on a Windows machine:

```
path=%path%;C:\Program Files\Java\j2re1.4.1\bin
```

GAUSS 6.0.25+ is required to use AD.

In order to use **AD**, the **AD** library must be active. This is done by including **ad** in the **library** statement at the top of your program or command file:

```
library ad;
```

This enables **GAUSS** to find the **AD** procedures.

You will also need to include the AD structure definition file

```
#include ad.sdf;
```

at the top of the command file.

The version number of each module is stored in a global variable:

_ad_ver 3×1 matrix, the first element contains the major version number of the AD module, the second element the minor version number, and the third element the revision number.

If you call for technical support, you may be asked for the version number of your copy of this module.

2.2 Using Algorithmic Derivatives

AD is a program for generating a **GAUSS** procedure to compute derivatives from a **GAUSS** procedure that computes a function value. If the input function procedure returns a scalar value given a $K \times 1$ input vector, the output derivative procedure computes a $1 \times K$ gradient. If the input function returns an $N \times 1$ vector given a $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes an $K \times 1$ input vector, the output derivative procedure computes and $K \times 1$ input vector $K \times 1$ inp

First, copy the input function procedure to a separate file. Second, from the command line enter

```
ad file_name d_file_name
```

where file_name is the name of the file containing the input function procedure, and d_file_name is the name of the file containing the output derivative procedure.

If the input function procedure is named fct, the output derivative procedure has the name d_fct if the function procedure has a single argument. If the function procedure has two arguments, the derivative procedure is given the name d_l_fct where the addition to the prefix indicates that the derivative is with respect to the first argument.

For example, put the following function into a file called lpr.fct:

```
proc lpr(x,z);
    local s,m,u;
    s = x[4];
    m = z[.,2:4]*x[1:3,.];
    u = z[.,1] ./= 0;
    retp(u.*lnpdfmvn(z[.,1]-m,s) + (1-u).*(lncdfnc(m/sqrt(s))));
endp;
```

Then enter the following at the GAUSS command line

```
library ad;
    ad lpr.fct d_lpr.fct;
If successful, the following is printed to the screen
    java -jar d:\gauss6.0\src\gauss_ad.jar lpr.fct d_lpr.fct
and the derivative procedure is written to file named d_lpr.fct:
    /* Version:1.0 - May 15, 2004 */
    /* Generated from:lpr.fct */
    /* Taking derivative with respect to argument 1 */
    Proc(1)=d_1!pr(x, z);
        Clearg _AD_fnValue;
            Local s, m, u;
            s = x[(4)];
            Local _AD_t1;
            AD_t1 = x[(1):(3),.];
            m = z[.,(2):(4)] * _AD_t1;
            u = z[.,(1)] ./= 0;
            AD_fnValue = (u .* lnpdfmvn(z[.,(1)] - m, s)) + ((1 - u) .*
    lncdfnc(m / sqrt(s)));
            /* retp(_AD_fnValue); */
            /* endp; */
            struct _ADS_optimum _AD_d__AD_t1 ,_AD_d_x ,_AD_d_s ,_AD_d_m
    ,_AD_d__AD_fnValue;
            /* _AD_d_AD_t1 = 0; _AD_d_s = 0; _AD_d_m = 0; */
        _AD_d__AD_fnValue = _ADP_d_x_dx(_AD_fnValue);
        _AD_d_s = _ADP_DtimesD(_AD_d__AD_fnValue,
    _ADP_DplusD(_ADP_DtimesD(_ADP_d_xplusy_dx(u .* lnpdfmvn( z[.,(1)] - m, s),
    (1 - u) .* lncdfnc(m / sqrt(s))), _ADP_DtimesD(_ADP_d_ydotx_dx(u, lnpdfmvn(
    z[.,(1)] - m, s)), _ADP_DtimesD(_ADP_internal(d_2_lnpdfmvn( z[.,(1)] - m, s)))
    s)), _ADP_d_x_dx(s)))), _ADP_DtimesD(_ADP_d_yplusx_dx(u .* lnpdfmvn(
    z[.,(1)] - m, s), (1 - u) .* lncdfnc(m / sqrt(s))),
    _ADP_DtimesD(_ADP_d_ydotx_dx(1 - u, lncdfnc(m / sqrt(s))),
    _ADP_DtimesD(_ADP_d_lncdfnc(m / sqrt(s)), _ADP_DtimesD(_ADP_d_ydivx_dx(m,
    sqrt(s)), _ADP_DtimesD(_ADP_d_sqrt(s), _ADP_d_x_dx(s)))))));
        _AD_d_m = _ADP_DtimesD(_AD_d__AD_fnValue,
    _ADP_DplusD(_ADP_DtimesD(_ADP_d_xplusy_dx(u .* lnpdfmvn( z[.,(1)] - m, s),
    (1 - u) .* lncdfnc(m / sqrt(s))), _ADP_DtimesD(_ADP_d_ydotx_dx(u, lnpdfmvn(
    z[.,(1)] - m, s)), _ADP_DtimesD(_ADP_internal(d_1_lnpdfmvn(z[.,(1)] - m, s)))
    s)), \_ADP\_DtimesD(\_ADP\_d\_yminusx\_dx(z[.,(1)], m), \_ADP\_d\_x\_dx(m))))),
    _ADP_DtimesD(_ADP_d_yplusx_dx(u .* lnpdfmvn( z[.,(1)] - m, s), (1 - u) .*
    lncdfnc(m / sqrt(s))), _ADP_DtimesD(_ADP_d_ydotx_dx(1 - u, lncdfnc(m / sqrt(s)
    )), _ADP_DtimesD(_ADP_d_lncdfnc(m / sqrt(s)), _ADP_DtimesD(_ADP_d_xdivy_dx(m,
```

If there's a syntax error in the input function procedure, the following is written to the screen

```
java -jar d:\gauss6.0\src\gauss_ad.jar lpr.fct d_lpr.fct
Command 'java -jar d:\gauss6.0\src\gauss_ad.jar cmlad3.fct d_lpr.fct' exit status 1
```

the **exit status 1** indicating that an error has occurred. The output file then contains the reason for the error:

```
/* Version:1.0 - May 15, 2004 */
/* Generated from:lpr.fct */

/* Taking derivative with respect to argument 1 */

proc lpr(x,z);
    local s,m,u;
    s = x[4];
    m = z[.,2:4]*x[1:3,.];
    u = z[.,1] ./= 0;
    retp(u.*lnpdfmvn(z[.,1]-m,s) + (1-u).*(lncdfnc(m/sqrt(s)));

Error: lpr.fct:12:63: expecting ')', found ';'
```

2.3 Naming Conventions for Procedures with Several Arguments

For a function procedure with a single argument,

```
proc fct(x);
  /* code */
endp;
```

in a file called, for example, fct.src with a single argument, the following

```
ad fct.src d_fct.src
```

produces a derivative procedure

```
proc d_fct(x);
  /* code */
endp;
```

in the file d_fct.src with the same single argument.

For a function procedure with two arguments,

```
proc fct(x,y);
  /* code */
endp;
```

produces a derivative procedure

```
proc d_1_fct(x);
  /* code */
endp;
```

where the "_1_" indicates the derivative is taken with respect to the first argument.

By default, the derivative is with respect to the first argument. To produce the derivative with respect to the second argument, add a "2" to the name of the file that will contain the derivative procedure. For example,

```
ad fct.src d_2_fct.src
```

The derivative procedure will then have the name

```
proc d_2_fct(b,x);
  /* code */
endp;
```

2.4 Adding a Derivative Function

The function procedure may contain calls to **GAUSS** functions that haven't yet been included in **AD**. Or it may contain calls to functions you have written. **AD** will need to know how to compute the derivatives of these functions before being able to produce the derivative procedure. This section describes several methods for doing this.

2.4.1 Calling Functions Returning Matrices with Dependent Columns

The derivative of the called function must be computed numerically. Add two procedures to the ad.src file in the src subdirectory:

```
proc _ADP_utility_userfct(x);
    retp(userfct(x));
endp;

proc d_userfct(x);
    retp(gradp4d(&_ADP_utility_userfct,x));
endp;

where userfct is the name of the called function. For example, for the GAUSS invpd function,
    proc _ADP_utility_invpd(x);
        retp(invpd(x));
    endp;

proc d_invpd(x);
    retp(gradp4d(&_ADP_utility_invpd,x));
endp;
```

2.4.2 Calling Functions Returning Matrices with Independent Columns

Most functions, for example, the **GAUSS log** function, return matrices that are independent. Their derivatives can be provided either numerically or analytically.

Analytical

For example, the following computes the derivatives for the **log** function. For your own function change "log" below to the name of your function, substitute the calculation of the derivative for the appropriate line, and add these procedures to the ad.src file:

```
proc(1) = d_log(x);
    retp(_ADP_external(_ADP_d_log(x)));
endp;

proc(1) = _ADP_d_log(x);
local xCols,xRows;
xCols = cols(x);
xRows = rows(x);
x = 1 ./ (ln(10) .* vec(x));
    retp(_ADP_putDiag(xCols|xCols|xRows|xRows,x));
endp:
```

Note that the input matrix is "vec-ed" after the number of rows and columns have been recorded.

Numerical for User-Provided Called Function

gradp1d is a function provided in **AD** for computing the derivative of a function returning a matrix with independent columns. Substitute your own called function name for "userfct".

```
proc(1) = d_userfct(x);
    retp(_ADP_external(_ADP_d_userfct(x)));
endp;

proc(1) = _ADP_d_userfct(x);
    local xCols,xRows;
    xCols = cols(x);
    xRows = rows(x);
    x = gradp1d(&userfct,x);
    retp(_ADP_putDiag(xCols|xCols|xRows|xRows,x));
endp;
```

Numerical for GAUSS Called Function

In order to handle a ${\bf GAUSS}$ function, a wrapper function needs to be written.

```
proc(1) = d_log(x);
    retp(_ADP_external(_ADP_d_log(x)));
endp;

proc _ADP_utility_log(x);
    retp(log(x));
endp;

proc(1) = _ADP_d_log(x);
    local xCols,xRows;
    xCols = cols(x);
    xRows = rows(x);
    x = gradp1d(&_ADP_utility_log,x);
    retp(_ADP_putDiag(xCols|xCols|xRows|xRows,x));
endp;
```

2.5 Running the Test Example

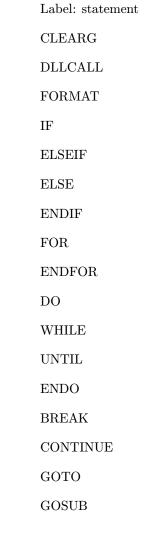
The example_procs subdirectory has a number of files containing function procedures (for example, test1.src). When run in **GAUSS** the example file test.e generates files

containing derivative procedures using the files with the function procedures (for example, $d_test1.src$).

Additionally, the example file d_test.e tests the accuracy of the resulting derivative procedures. Thus after running test.e, run d_test.e and an accuracy report is printed to the screen.

2.6 Disallowed GAUSS Constructions

The following GAUSS language constructions are not allowed in the input procedure



2.7 References

Griewank, Andreas, Principles and Techniques of Algorithmic Differentiation, SIAM,

$2. \ \textit{GETTING STARTED}$

Chapter 3

Algorithmic Derivatives Reference

Generates a procedure for computing derivatives from a procedure that computes a function.

Library

ad

Format

ad infile_name outfile_name

Input

```
infile_name string, name of file containing procedure computing function
outfile_name string, name of file into which the derivative procedure is to be put
```

Example

```
library ad
ad fct.src d_fct.src
```

Computes the gradient vector defined in a procedure. Single-sided (forward difference) gradients are computed.

Library

ad

Format

```
g = GRADP1D(\&fct,x)
```

Input

```
&fct a pointer to a procedure that evaluates a function given x proc fct(x);

/* function evaluation here */

retp(result);
endp;
```

This function must return a vector or a matrix with independent columns.

 $K \times 1$ vector, values at which to evaluate the function

Output

 $M \times 1$ vector, derivatives of function evaluated at x where M is the number of columns of the matrix returned by fct.

Example

See also

```
gradp4d, \, gradp4d\_2\_1, \, gradp4d\_2\_2, \, gradp, \, hessp
```

Computes the gradient vector or matrix (Jacobian) of a matrix-valued function defined in a procedure. Single-sided (forward difference) gradients are computed.

Library

ad

Format

```
g = GRADP4D(\&fct,x)
```

Input

 $K \times J$ vector, values at which to evaluate the function

Output

 \boldsymbol{x}

g scalar, $1 \times K$ vector, $Q \times K$ matrix, $L \times Q \times K$ array or $P \times L \times Q \times K$ array, derivatives of function evaluated at x.

If x is a $K \times 1$ vector and fct(x) is a 1×1 scalar, the result g is row vector [1, K] of gradients

If x is a $K \times 1$ vector and fct(x) is an $N \times 1$ vector, the result g is matrix [N, K] of cross gradients

If x is a matrix $K \times J$ and fct(x) is an $N \times 1$ vector, the result g is 3D matrix [J, N, K]

If x is a matrix $K \times J$ and fct(x) is a matrix $N \times M$, the result g is 4D matrix [M, J, N, K]

Remarks

gradp4d will return a row for every row that is returned by fct. For instance, if fct returns a 1×1 result, then **gradp4d** will return a $1 \times K$ row vector. This allows the same function to be used where N is the number of rows in the result returned by fct. Thus, for instance, **gradp4d** can be used to compute the Jacobian matrix of a set of equations.

Example

```
proc myfunc(x);
  retp(x*x');
endp;
x0 = \{ 0.1 0.2 0.3,
      0.4 0.5 0.6 };
gradp4d(&myfunc,x0);
  Plane [1,1,.,.]
   0.20 0.00
   0.40 0.10
  Plane [1,2,.,.]
   0.40 0.00
   0.50 0.20
  Plane [1,3,.,.]
   0.60 0.00
   0.60 0.30
   Plane [2,1,.,.]
   0.40 0.10
   0.00 0.80
  Plane [2,2,.,.]
   0.50 0.20
   0.00 1.00
  Plane [2,3,.,.]
    0.60 0.30
    0.00 1.20
```

See also

gradp1d, gradp4d_2_1, gradp4d_2_2, gradp, hessp

Computes 4-dimensional numerical derivatives.

Library

ad

Format

```
g = GRADP4D_2_1(\&fct,x,y)
```

 $M \times N$ matrix

Input

```
&fct a pointer to a procedure that evaluates a function given x and y proc fct(x,y);

/* function evaluation here */

retp(result);
endp;

K \times L matrix, values at which to evaluate the function
```

Output

y

g scalar, $1 \times K$ vector, $Q \times K$ matrix, $L \times Q \times K$ array or $P \times L \times Q \times K$ array, derivatives of function evaluated at x.

If x is a $K \times 1$ vector and fct(x,y) is a 1×1 scalar, the result g is row vector [1, K] of gradients

If x is a $K \times 1$ vector and fct(x,y) is an $N \times 1$ vector, the result g is matrix [N,K] of cross gradients

If x is a matrix $K \times J$ and fct(x,y) is an $N \times 1$ vector, the result g is 3D matrix [J,N,K]

If x is a matrix $K \times J$ and fct(x,y) is a matrix $N \times M$, the result g is 4D matrix [M,J,N,K]

Remarks

gradp4D_2_1 will return a row for every row that is returned by fct. For instance, if fct returns a 1×1 result, then **gradp4D_2_1** will return a $1 \times K$ row vector. This allows the same function to be used where N is the number of rows in the result returned by fct. Thus, for instance, **gradp4D_2_1** can be used to compute the Jacobian matrix of a set of equations.

Example

```
proc myfunc(x,y);
   retp(x * y);
endp;
x0 = \{ 0.1 0.2 0.3,
       0.4 0.5 0.6 };
y = \{ 14,25,36 \};
gradp4d_2_1(&myfunc,x0,y);
   Plane [1,1,.,.]
    1.00 0.00
    0.00 1.00
   Plane [1,2,.,.]
    2.00 0.00
    0.00 2.00
   Plane [1,3,.,.]
    3.00 0.00
    0.00 3.00
   Plane [2,1,.,.]
    4.00 0.00
    0.00 4.00
   Plane [2,2,.,.]
    5.00 0.00
    0.00 5.00
   Plane [2,3,.,.]
    6.00 0.00
    0.00 6.00
```

See also

gradp4d_2_2, gradp4d, gradp, hessp

Computes 4-dimensional numerical derivatives.

Library

ad

Format

```
g = GRADP4D_2_2(\&fct,x,y)
```

Input

```
& fct a pointer to a procedure that evaluates a function given x and y proc fct(x,y);

/* function evaluation here */

retp(result);
endp;

x \qquad M \times N \text{ matrix}

y \qquad K \times L \text{ matrix}, values at which to evaluate the function
```

Output

g scalar, $1 \times K$ vector, $Q \times K$ matrix, $L \times Q \times K$ array or $P \times L \times Q \times K$ array, derivatives of function evaluated at y.

If y is a $K \times 1$ vector and fct(x,y) is a 1×1 scalar, the result g is row vector [1,K] of gradients

If y is a $K \times 1$ vector and fct(x,y) is an $N \times 1$ vector, the result g is matrix [N,K] of cross gradients

If y is a matrix $K \times J$ and fct(x,y) is an $N \times 1$ vector, the result g is 3D matrix [J,N,K]

If y is a matrix $K \times J$ and fct(x,y) is a matrix $N \times M$, the result g is 4D matrix [M,J,N,K]

Remarks

gradp4D_2_2 will return a row for every row that is returned by fct. For instance, if fct returns a 1×1 result, then **gradp4D_2_2** will return a $1 \times K$ row vector. This allows the same function to be used where N is the number of rows in the result returned by fct. Thus, for instance, **gradp4D_2_2** can be used to compute the Jacobian matrix of a set of equations.

Example

```
proc myfunc(x,y);
   retp(x * y);
endp;
x = \{ 0.1 0.2 0.3,
       0.4 0.5 0.6 };
y0 = \{ 14,25,36 \};
gradp4d_2_2(&myfunc,x,y0);
   Plane [1,1,.,.]
    0.10 0.20 0.30
    0.40 0.50 0.60
   Plane [1,2,.,.]
    0.00 0.00 0.00
    0.00 0.00 0.00
   Plane [2,1,.,.]
    0.00 0.00 0.00
    0.00 0.00 0.00
   Plane [2,2,.,.]
    0.10 0.20 0.30
    0.40 0.50 0.60
```

See also

gradp4D_2_1, gradp4d, gradp, hessp

GRADP4D_2_2

 $3. \ ALGORITHMIC \ DERIVATIVES \ REFERENCE$

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